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development environment, is based on a distributed control  
architecture: each object/model can be individually controlled  
via an embedded script, a plugin, a ROS or BlueZero node, a  
remote API client, or a custom solution. This makes  
CoppeliaSim very versatile and ideal for multi-robot  
applications. Controllers can be written in C/C++, Python,  
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PyRep PyRep is a toolkit for robot learning research, built on top of CoppeliaSim (previously called V-REP). NOTE: V-REP

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has recently been changed to CoppeliaSim.

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