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```
function p=newtonPoly(a,xData,x) % Returns value of Newton's polynomial at x.  
%USAGE:p=newtonPoly(a,xData,x) % a = coefficient array of the polynomial; % must be computed first by  
newtonCoeff. % xData = x-coordinates of data points. n = length(xData); p = a(n); for k=1:n-1; p = a(n-k)  
+ (x - xData(n-k))*p; end.
```

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and hence it is a need to seek approximate solutions by means of numerical methods. Delay. differential equations (DDEs) form an important class of dynamical systems. They often arise.

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Ingredients: Broken wheat: 1 cup Milk: 3 cups (pasturised or boiled) Jaggery (traditional unrefined cane sugar)- 2 cups (or according to taste) Ghee: cup Water: 3 cups Cashews: cup Raisins (draksha or dry grapes): cup Almonds: cup Cardamom: (powdered) - tea spoon Preparation Method: Heat a frying pan on stove.

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