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Wavelet Based Denoising of Audio Signals using MATLAB & SIMULINK **Standard HW Problem #1: PID and Root Locus Pole Placement for the Inverted Pendulum on a Cart [Control Bootcamp]** ME565 Lecture 20: Numerical Solutions to PDEs Using FFT **SHORTCUT TRICKS to solve Signals and Systems questions | GATE & ESE exam** Lecture on antenna engineering: Floquet theory and unit cell analysis *Developing Machine Learning and Deep Learning Algorithms Using MATLAB Laplace Transform using Matlab* Signals Systems Chaparro Solution Manual

Chaparro-Akan — Signals and Systems using MATLAB 0.7 0.6 Differential and difference equations — Find the ordinary differential equation relating a current source  $i_s(t) = \cos(0t)$  with the current  $i_L(t)$  in an inductor, with inductance  $L = 1$  Henry, connected in parallel with a resistor of  $R = 1$  (see Fig. 3).

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Chaparro — Signals and Systems using MATLAB 0.9 0.9 (a) If  $w = e^z$  then  $\log(w) = z = 1 + j1$  given that the log and exp functions are the inverse of each other. The real and imaginary of  $w = e^z = e^1 e^{j1} = e \cos(1) + j e \sin(1)$  |  $\{z\}$  real part +  $j \{z\}$  imaginary part (b) The imaginary parts are cancelled and the real parts added twice in  $w + w = 2\text{Re}[w] = 2e \cos(1)$

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Chaparro-Akan — Signals and Systems using MATLAB 0.4 0.3 Use Euler's identity to (a) show the identities (i)  $\cos(\theta + \phi) = \cos(\theta)\cos(\phi) - \sin(\theta)\sin(\phi)$

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(ii)  $\sin(\theta + \phi) = \sin(\theta)\cos(\phi) + \cos(\theta)\sin(\phi)$ ; (b) find an expression for  $\cos(\theta)\cos(\phi)$ , and for  $\sin(\theta)\sin(\phi)$ . Answers:  $e^{j\theta}e^{j\phi} = \cos(\theta + \phi) + j\sin(\theta + \phi) = [\cos(\theta)\cos(\phi) - \sin(\theta)\sin(\phi)] + j[\sin(\theta)\cos(\phi) + \cos(\theta)\sin(\phi)]$ .

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Chaparro — Signals and Systems using MATLAB. 2.10. 2.10 The input to all the systems is  $x(t) = \cos(t)$ ,  $-\pi < t < \pi$  (a) The system is non-linear, as the output  $y(t) = \cos^2(t) = 0.5(1 + \cos(2t))$  ...

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