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amplifier angle applied approximation assumed asymptotes becomes block diagram Bode plot branches called Chapter characteristic equation closed-loop coefficients compensated system compensator complex components computed condition Consider constant contour control system corresponding curve damping defined derivative describing desired ...

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The problem is that the book is boring. Nise's Control System Engineering is much more readable. Regarding the introduction of non-linear, optimal, robust, and adaptive control I think that the best is to go to the specialised sources.