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This volume is a selection of papers from a NATO Advanced Study Institute held in July 1989 with a focus on active perception and robot vision. The papers deal with such issues as motion understanding, 3-D data analysis, error minimization, object and environment modeling, object detection and recognition, parallel and real-time vision, and data fusion.

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Action and perception are tightly coupled. This has been developed most comprehensively with respect to vision (active vision) where an agent (animal, robot, human, camera mount) changes position to improve the view of a specific object, or where an agent uses movement to perceive the environment (e.g., a robot avoiding obstacles).

Active perception - Wikipedia

As outlined in a research paper presented at the 2019 International Conference on Robotics and Automation (ICRA) in Montreal, the project's active perception approach is the first in the world to focus on real-time grasping by stepping away from a static camera position or fixed data collecting routines.

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artificial agent necessarily must include active perception. A multitude of ideas and methods for how to accomplish this have already appeared in the past, their broader utility perhaps impeded by insufficient computational power or costly hardware.

Revisiting active perception | SpringerLink

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Yezhou: Tech talk "Vision-Language integration challenges and needs in Robotics" at the 3rd integrating Vision and Language training school, Sep 5th, Athens, Greece. Yezhou: Tech talk "Active Perception Beyond Appearance, and its Robotic Applications" at the Brain team, Google Inc.

Yezhou Yang

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Overview . The Interactive Perception and Robot Learning Lab is part of the Stanford AI Lab at the Computer Science Department. We seek to understand the underlying principles of robust

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sensorimotor coordination by implementing them on robots.

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